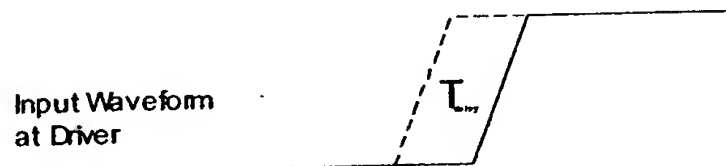


FIG. 1



$$T_{driver} = T_{desired} - T_{delay}$$

FIG. 2

$T_{\text{measure}}$   
At Comparator



$$T_{\text{receive}} = T_{\text{measure}} + T_{\text{delay}}$$

FIG. 3

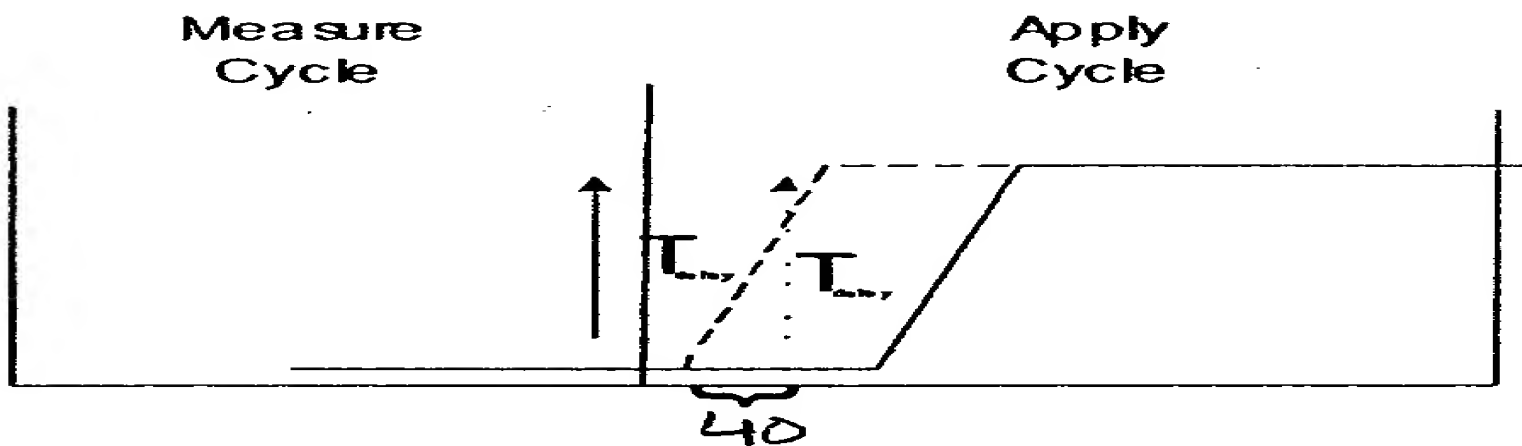


FIG. 4

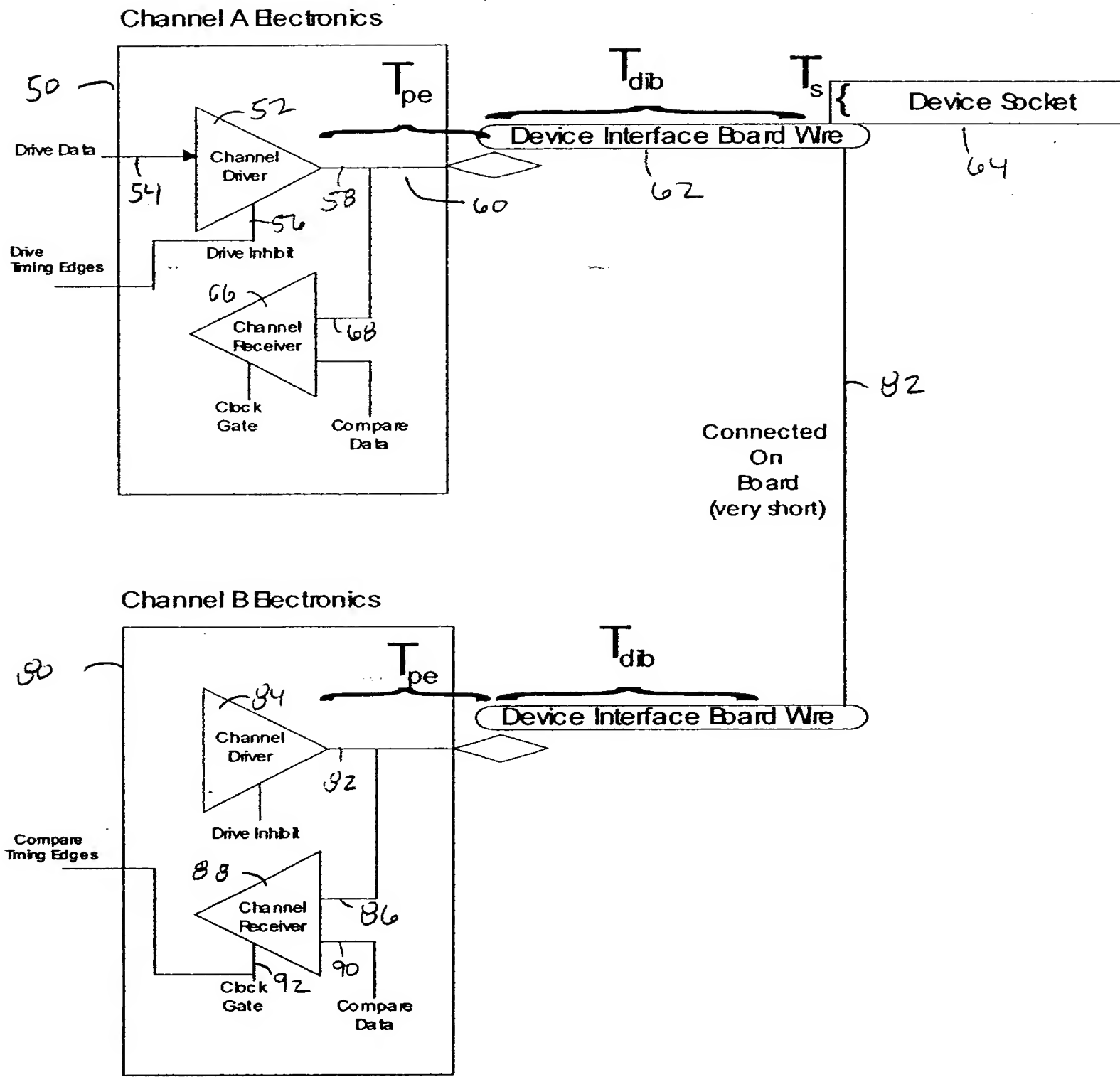


FIG. 5